

ANGp101/RES

closed loop goniometer with resistive encoder for Φ -positioning

Technical Specifications

Technology		Compatibility with Electronics	
travel mechanism	inertial piezo drive	ANC350 piezo positioning controller	ANC350/RES
Size and Dimensions		Working Conditions	
footprint; height	24 x 24; 11 mm	mounting orientation	axis horizontal
maximum size	28.9 x 26.5; 11.6 mm	magnetic field range	0 .. 31 T
distance center of rotation to bottom	62 mm (above center)	temperature range (/LT, /LT/HV, /LT/UHV)	10 mK .. 373 K
weight	18 g	max. bake out temperature (/UHV, /LT/UHV)	150 °C
Coarse Positioning Mode		Position Encoder	
	@ 300 K	@ 4 K	
input voltage range	0 .. 60 V	0 .. 60 V	readout mechanism
typical actuator capacitance	1.05 μ F	0.15 μ F	resistive sensor
travel range (step mode)	5.4°	5.4°	sensor power (when measuring)
typical minimum step size	0.1 m°	20 μ °	1 μ W .. 1 mW
maximum drive velocity	\approx 1°/s		encoded travel range
Fine Positioning Mode		full travel	
fine positioning range	no fine positioning capability		
Materials (non-magnetic)		sensor resolution	
positioner body	titanium (upgrade option: beryllium copper)	0.1 m°	
actuator	PZT ceramics	repeatability	
connecting wires	insulated twisted pair, copper	1.2 μ m	
Load (@ ambient conditions)		linearity (over full travel)	
	mounting orientation: axis horizontal	< 1%	
maximum load	1 N (100 g)	absolute accuracy	
maximum dynamic force along the axis	2 N	typically < 1% of travel range	
Mounting		Connectors and Feedthroughs	
from the top	2 through holes dia 2.2 mm, cntrbr. f. M2	/RT, /LT Versions	all /HV, /UHV Versions
from the bottom	2 threads M2.5 x 6 mm	connector type	2-pole pin plug, \emptyset 0.5 mm, d = 2 mm, 30 cm cable with connector
load on top	6 threads M2 x 3 mm	encoder connector	additional 3-pole plug
Article Numbers		electrical feedthrough solution	VFT/LT
/RT Version	1002793	VFT/HV, VFT/UHV	
/HV Version	1002795		
/UHV Version	1002797		
/LT Version	1002799		
/LT/HV Version	1002801		
/LT/UHV Version	1002803		

Technical Drawings

