

ECGp5050

nanoprecise open loop stepper goniometer providing Φ -positioning

| Technical Specifications | | | | | |
|---------------------------------------|---|---|--------------|-------------------------------|----------------------------|
| Technology | | Compatibility with Electronics | | | |
| travel mechanism | inertial piezo drive | ECC100 piezo positioning controller | | all versions | |
| Size and Dimensions | | Working Conditions | | | |
| footprint; height | 50 x 55.4; 17 mm | mounting orientation | | arbitrary | |
| maximum size | 50 x 61.1; 19.4 mm | temperature range (/RT, /HV, /UHV) | | 0100 °C | |
| distance center of rotation to bottom | 94 mm | max. bake out temperature (/UHV) | | 150 °C | |
| weight (aluminum/stainless steel) | 137 / 247 g | minimum pressure (/RT) | | 1E-4 mbar | |
| Coarse Positioning Mode | | minimum pressure (/HV) minimum pressure (/UHV) | | 1E-8 mbar 5E-11 mbar | |
| input voltage range | 0 60 V | . , | | | |
| typical actuator capacitance | 1.05 μF | Accuracy of Movement | | | |
| travel range (step mode) | 10° | repeatability of step sizes | | typically 5 % over full range | |
| typical minimum step size | 0.1 m° | forward / backward step asymmetry | | 10% | |
| maximum drive velocity (@ 45 V) | 3 °/s | , , , | • | | |
| * , | • | Position Encoder | | | |
| Fine Positioning Mode | | encoder options | | - | |
| input voltage range | 0 100 V | | | | |
| fine positiong range | 0 1.1 m° | Connectors and Feedthroughs | /RT Versions | S | all /HV, /UHV Versions |
| fine positioning resolution | μ° | connector type | 14-pole coni | nector | 15-pin D-Sub connector |
| | | | 50 cm cable | with connector | 50 cm cable with connector |
| Materials | | electrical feedthrough solution | | | VFT/HV, VFT/UHV |
| positioner body (/RT) | aluminum | | | | |
| positioner body (/HV, /UHV) | stainless steel | | | | |
| actuator | PZT ceramics | | | | |
| connecting wires | insulated twisted pair, copper | | | | |
| bearings | stainless steel | | | | |
| Load (@ ambient conditions) | mounting orientation: axis horizontal | | | | |
| maximum load | 10 N (1 kg) | | | | |
| maximum dynamic torque around axis | 7 Ncm | | | | |
| /HL/RT - ambient conditions | 35 Ncm | | | | |
| Mounting | | | | | |
| from the top | 4 through holes dia 2.2 mm, cntrbr. f. M2 | | | | |
| from the bottom | 4 threads for M2.5 x 2 mm | | | | |
| load on top | 12 threads M2 x 2.3 mm | | | | |
| load at the front | L-bracket | | | | |
| Article Numbers | | | | | |
| /RT version aluminum | 1006222 | | | | |
| /HV version stainless steel | 1006226 | | | | |
| /UHV version stainless steel | 1006228 | | | | |
| /HL/RT version | 1008842 | | | | |
| | | | | | |



