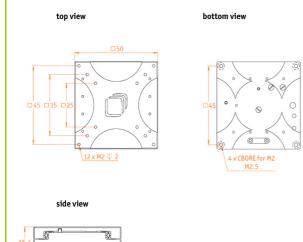
ECSxy5050/NUM(+)

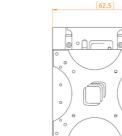
nanoprecise closed loop stepper positioner for linear, horizontal motion with optoelectronic sensor

Technical Specifications

Technology		Compatibility with Electronics	
travel mechanism	inertial piezo drive	ECC100 piezo positioning controller	all versions
Size and Dimensions		Working Conditions	
footprint; height	50 x 50; 16.4 mm	mounting orientation	arbitrary
maximum size	62.5 x 62.5; 16.4 mm	temperature range (/RT, /HV, /UHV)	0100 °C
weight	111 g	minimum pressure (/RT)	1E-4 mbar
Coarse Positioning Mode			
input voltage range	0100 V		
typical actuator capacitance	0.6 μF @ 300K		
travel range (step mode)	25 x 25 mm²	Accuracy of Movement	
typical minimum step size	0.05 μm	yaw angle (over 10 mm travel)	< 0.1 mrad
maximum drive velocity (@ 45 V)	4.5 mm/s	pitch angle (over 10 mm travel)	< 0.1 mrad
, <u>,</u>	,	roll angle (over 10 mm travel)	< 0.1 mrad
Fine Positioning Mode		Position Encoder	
input voltage range	060V	readout mechanism	optoelectronic: /NUM & /NUM+/(U)HV
fine positiong range	0 1.6 µm	sensor power (when measuring)	/NUM: 300 mW & /NUM+/(U)HV: 50 mW
fine positioning resolution	sub-nm	encoded travel range	entire travel
5		wavelength of illumination	870 nm
Materials		sensor resolution	1 nm
positioner body (/RT)	aluminum	repeatability	50 nm
actuator	PZT ceramics	absolute accuracy	< 0.01% of travel range
connecting wires	insulated twisted pair, copper		
bearings	stainless steel		
Load (@ ambient conditions)	mounting orientation: axis horizontal	Connectors and Feedthroughs	/RT Versions
maximum load	150 N (15 kg)	connector type	two 14-pole connectors
maximum dynamic force along the axis	2 N		50 cm cable with connector
		electrical feedthrough solution	
Mounting		Article Numbers	
from the top	4 through holes dia 2.2 mm, cntrbr. f. M2	/RT version aluminum	1011873
from the bottom	4 threads for M2.5 x 2 mm		
load on top	12 threads M2 x 2.3 mm		
	L-bracket		

Technical Drawings





inner position

12.5

0

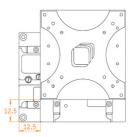
R

0

0

(62.5)

outer position



All rights, including rights created by patent grant or registration of a utility model or design as well as rights of technical modifications are reserved. Delivery subject to availability. Designations may be trademarks, the use of which by third parties for their own purposes may violate the rights of the trademark owners. © attocube systems AG 2001-2016. Issued 2016/4

